



Flexible and efficient automation using TwinCAT MTP and CoAgent

TwinCAT CoAgent
Module Type Package (MTP)

FIIF, 12.06.2025, Tampere

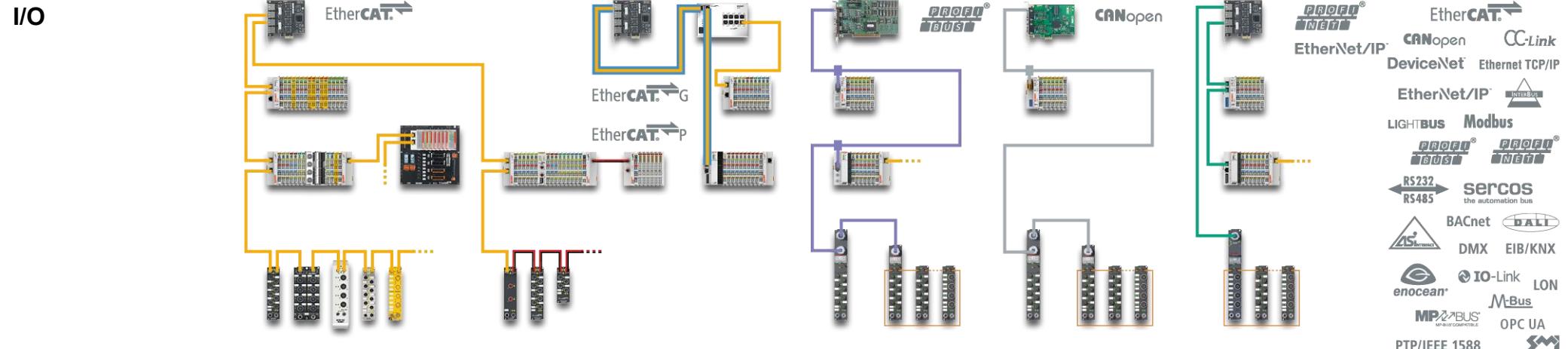
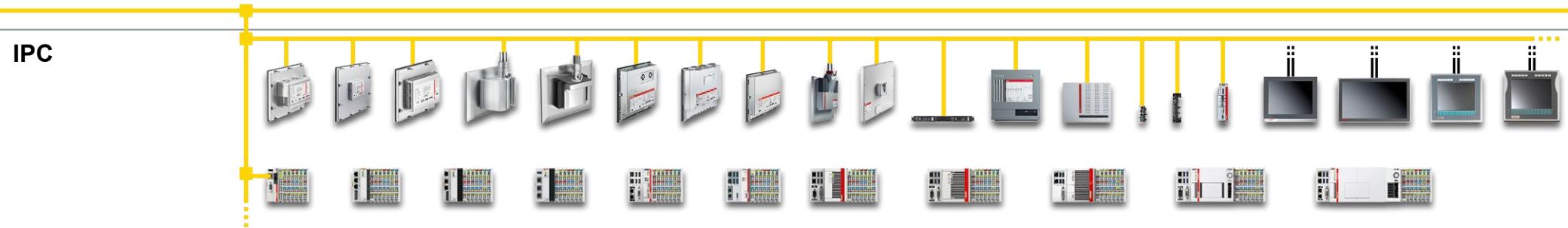
Dr. Mikko Heikkilä &
Tuure Takala
Beckhoff Automation Oy



System overview

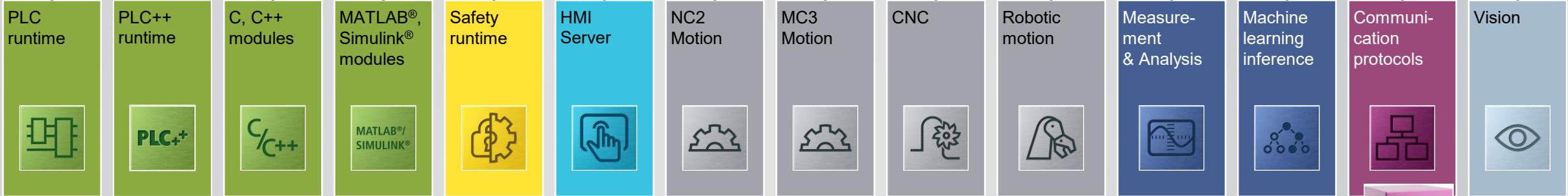
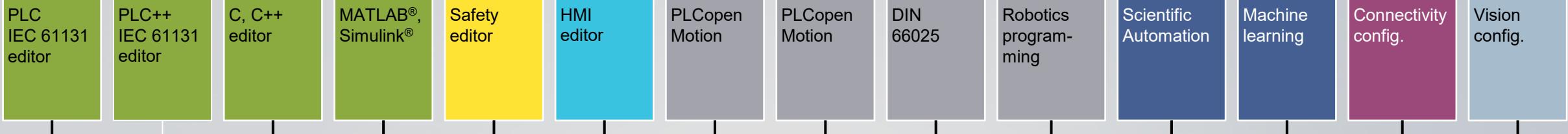
Building blocks for automation and machine builders

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TwinCAT Engineering



TwinCAT Runtime



Operating System

Windows

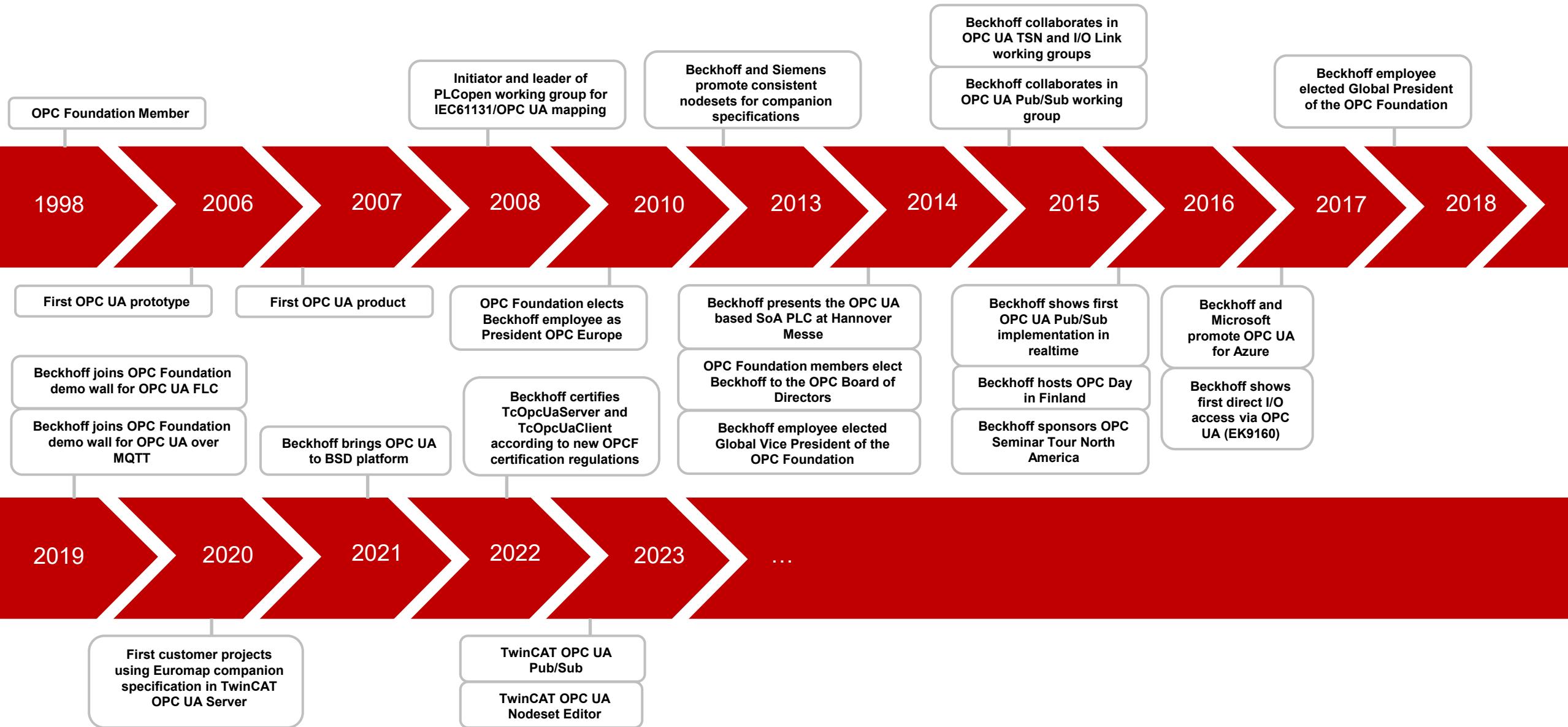
Linux®

TwinCAT/BSD

TwinCAT/RTOS

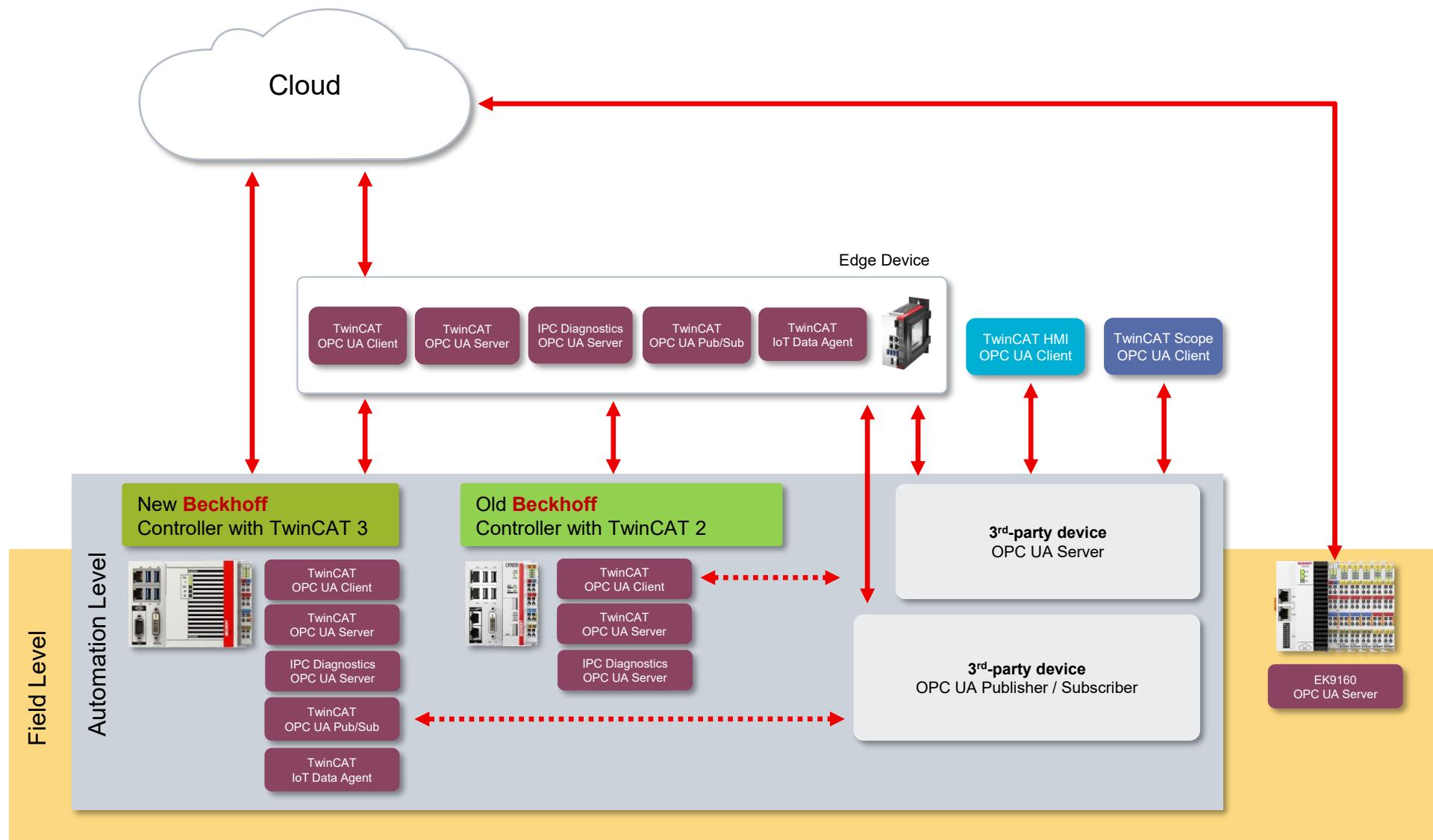
Beckhoff and OPC Foundation history

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OPC UA enabled products for every use case (since 2006)

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CoAgent



Agentic Automation

Democratization of AI through natural language

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- LLMs are the most fundamental democratization process of AI
- Everybody can use LLMs without being an AI expert

- Use cases in Automation
 - Code generation
 - Documentation
 - ...
 - Human-centric interface to software

What is the most natural way for humans to interact with AI?

The most natural way for humans to interact with AI is **through multimodal, context-aware, and adaptive communication**—mimicking how humans naturally engage with each other. Below are key dimensions that define this natural interaction:

1. Natural Language Conversation

- **Text and Voice Interfaces:** Typing or speaking in one's native language is currently the most intuitive way for people to interact with AI, especially when powered by large language models like ChatGPT.
- **Context Retention:** AI systems that remember past interactions and use them to shape current responses create more fluid and meaningful conversations.

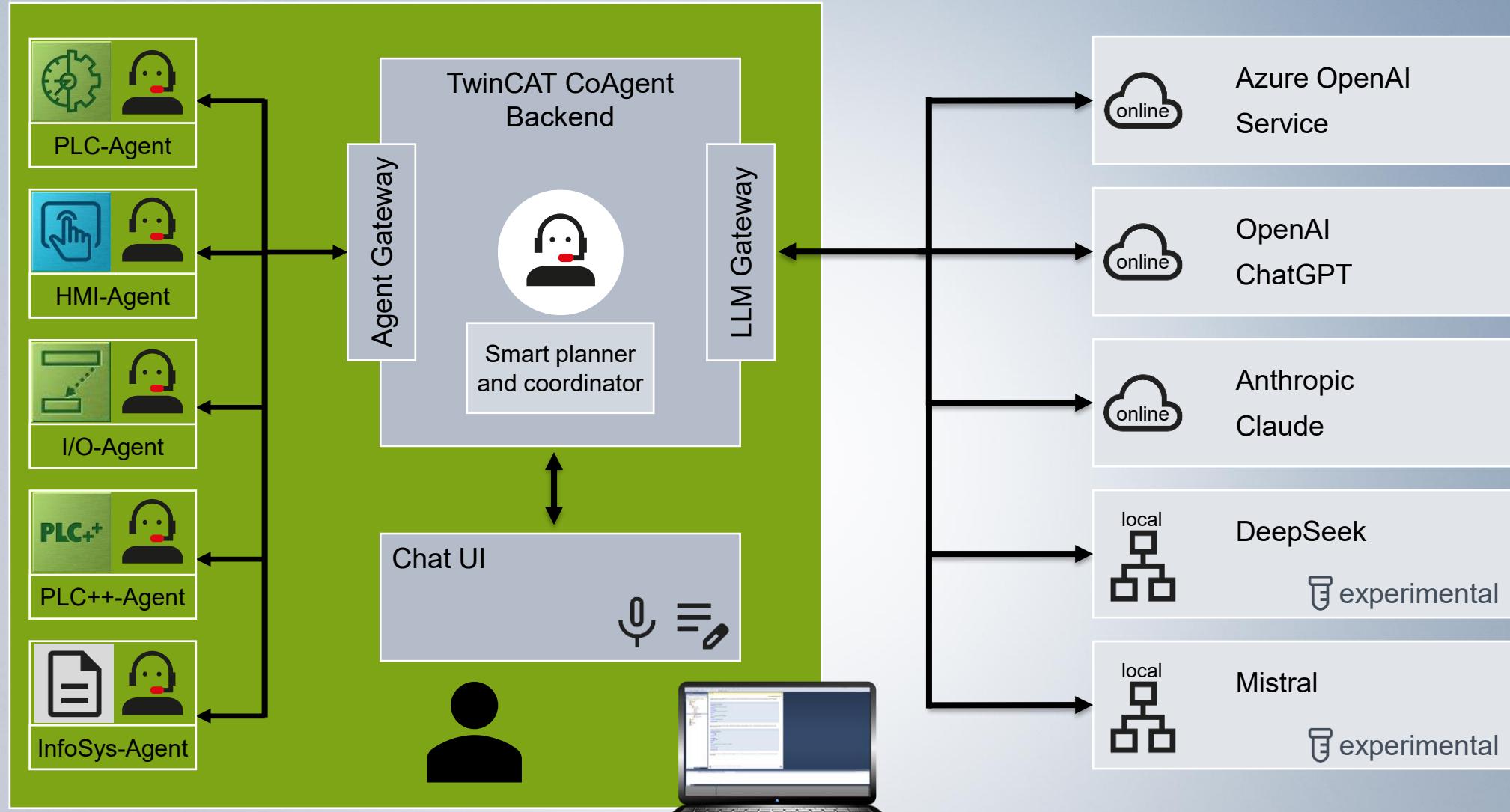
2. Multimodal Interaction

- **Speech + Vision + Gesture:** Combining spoken language with visual recognition (e.g., pointing, facial expressions, eye tracking) allows more human-like interaction.
- **Examples:**
 - A person asks an AI assistant to "move that box," while pointing.
↓
 - AR/VR interfaces where users speak and gesture to interact with virtual objects.

TwinCAT CoAgent

Smart Agents for Automation Engineering

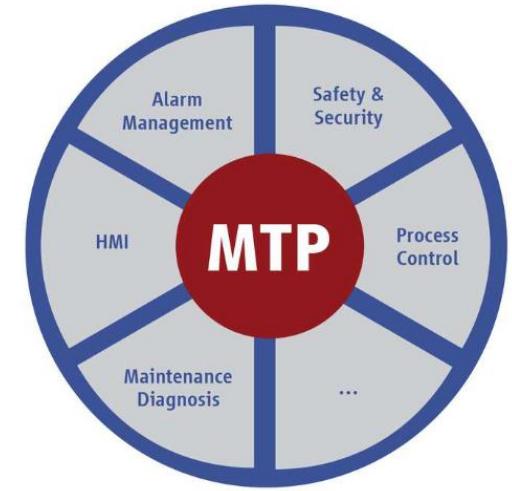
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About MTP (Module Type Package)

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- A modularization concept for development of a modular plants
 - Addressing primarily the segment of process industry
 - Standardization initially in VDI/VDE/NAMUR 2658 (since 2014)
 - Ongoing development of the international standard IEC 63280 (MTP 2.0 specification, soon to be published)
 - Current standardization is driven by PROFIBUS User Organization (PNO) part of PI
-
- Enables vendor-independent integration and control of plant functional modules
 - Standardized interfaces and communication from a higher-level control system (DCS, SCADA)



- NAMUR = The User Association of Automation Technology in Process Industries
- ZVEI = The (Manufacturers) Association of the Electrical and Digital Industry



Architecture and components

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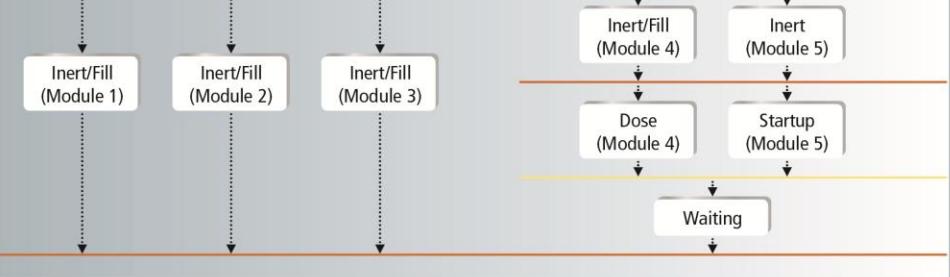
Process
Orchestration Layer
(POL)

Distributed Control System

Visualization

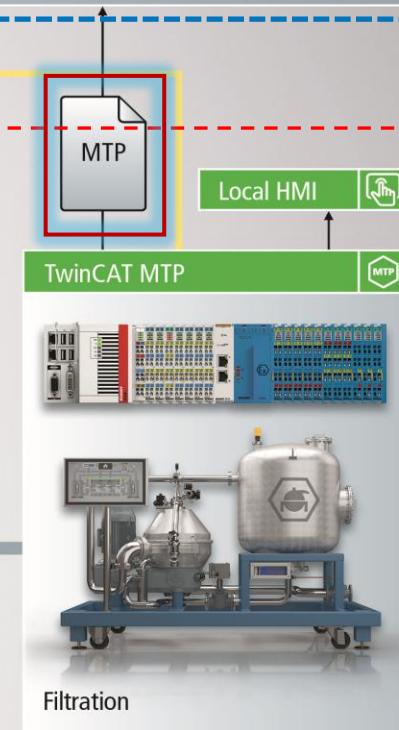
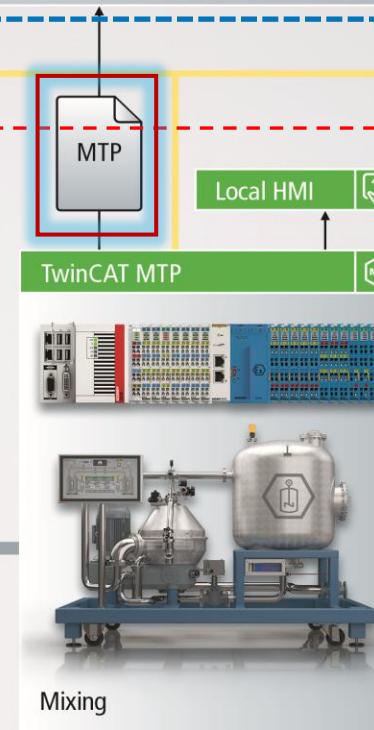
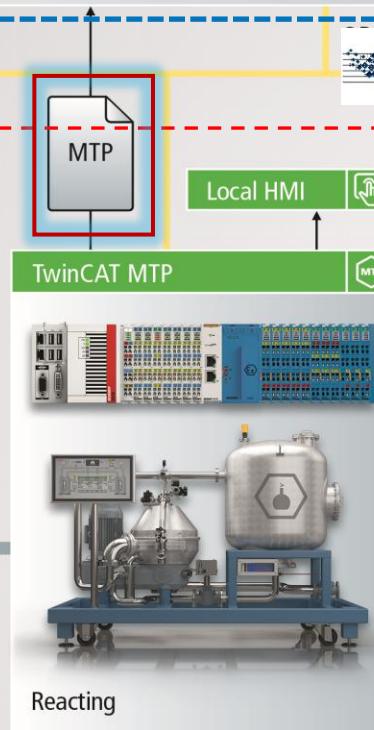
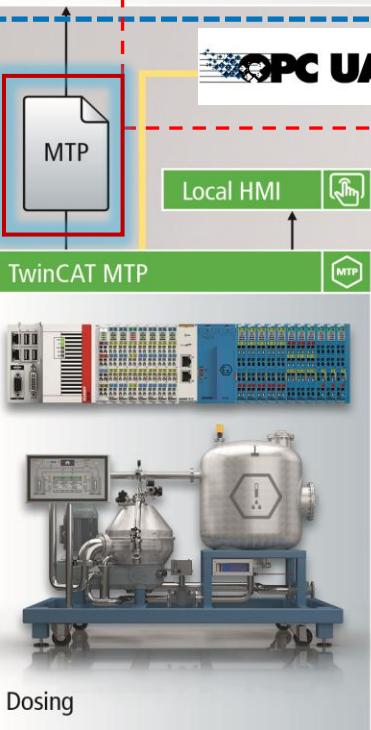


Orchestration



Plant Engineering

Process Equipment Assembly
(PEA)

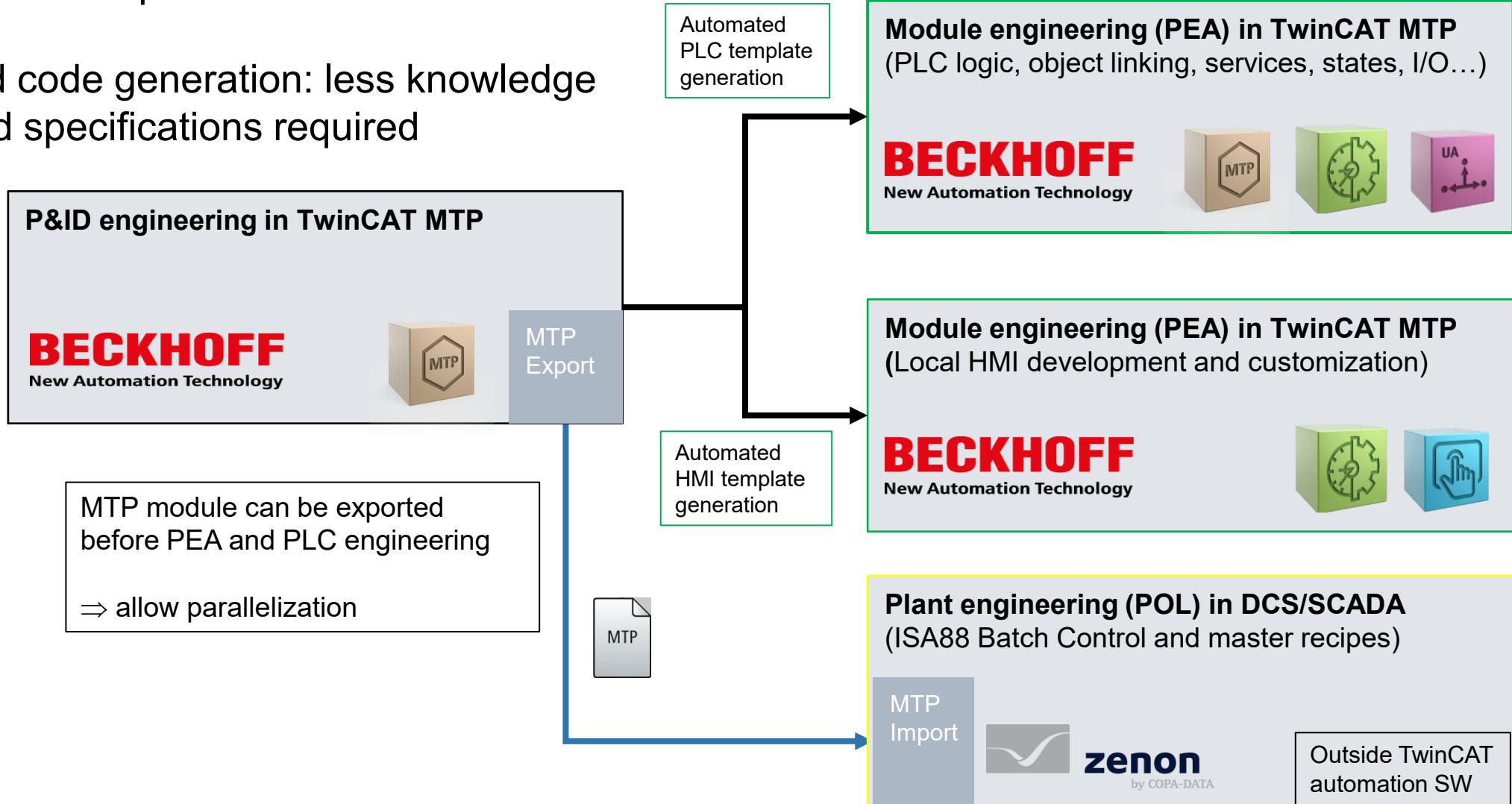


Module Engineering

Development phases

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- An efficient development workflow!
- Automated code generation: less knowledge of standard specifications required

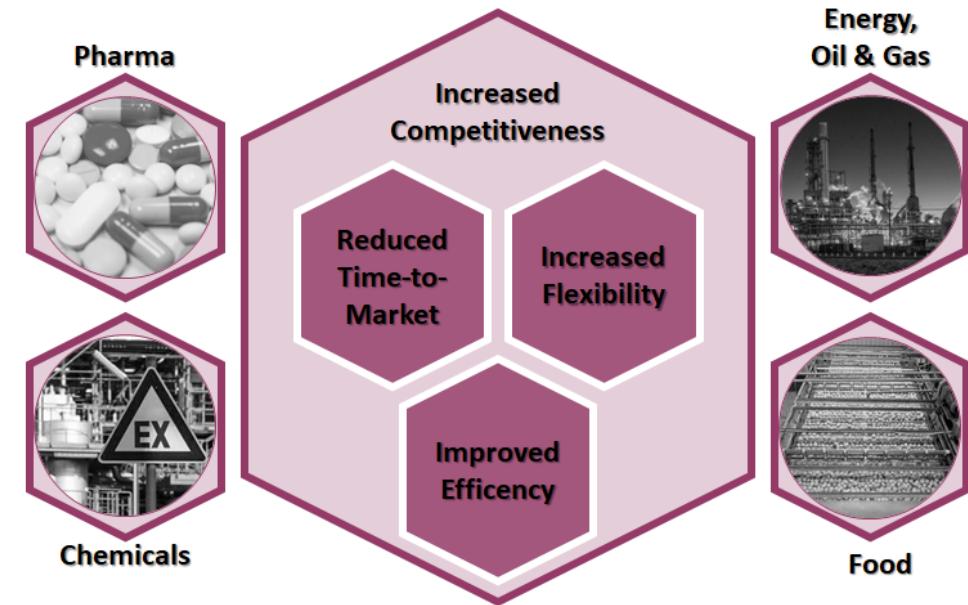


What are the benefits of MTP?

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- Shorter Time-to-Market (50% reduction)
- Reduced engineering effort by 70%
- Increased flexibility by 80%

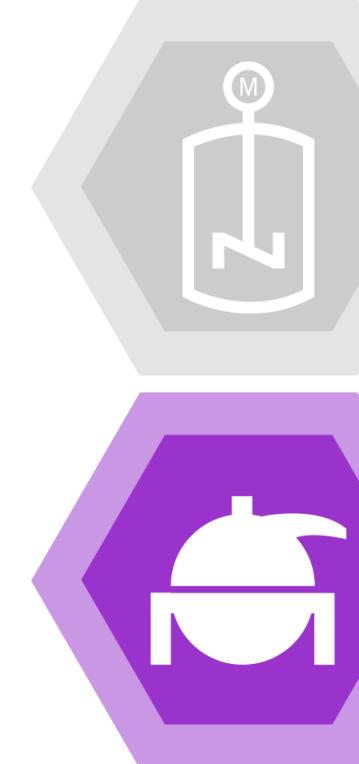
- Modularization also improves:
 - Module expandability and reusability
 - => Improved support for small batch production (e.g. pharmaceutical industry)
 - Maintenance (e.g. faster time-to-repair)



=> Overall, higher development efficiency and lower production costs!

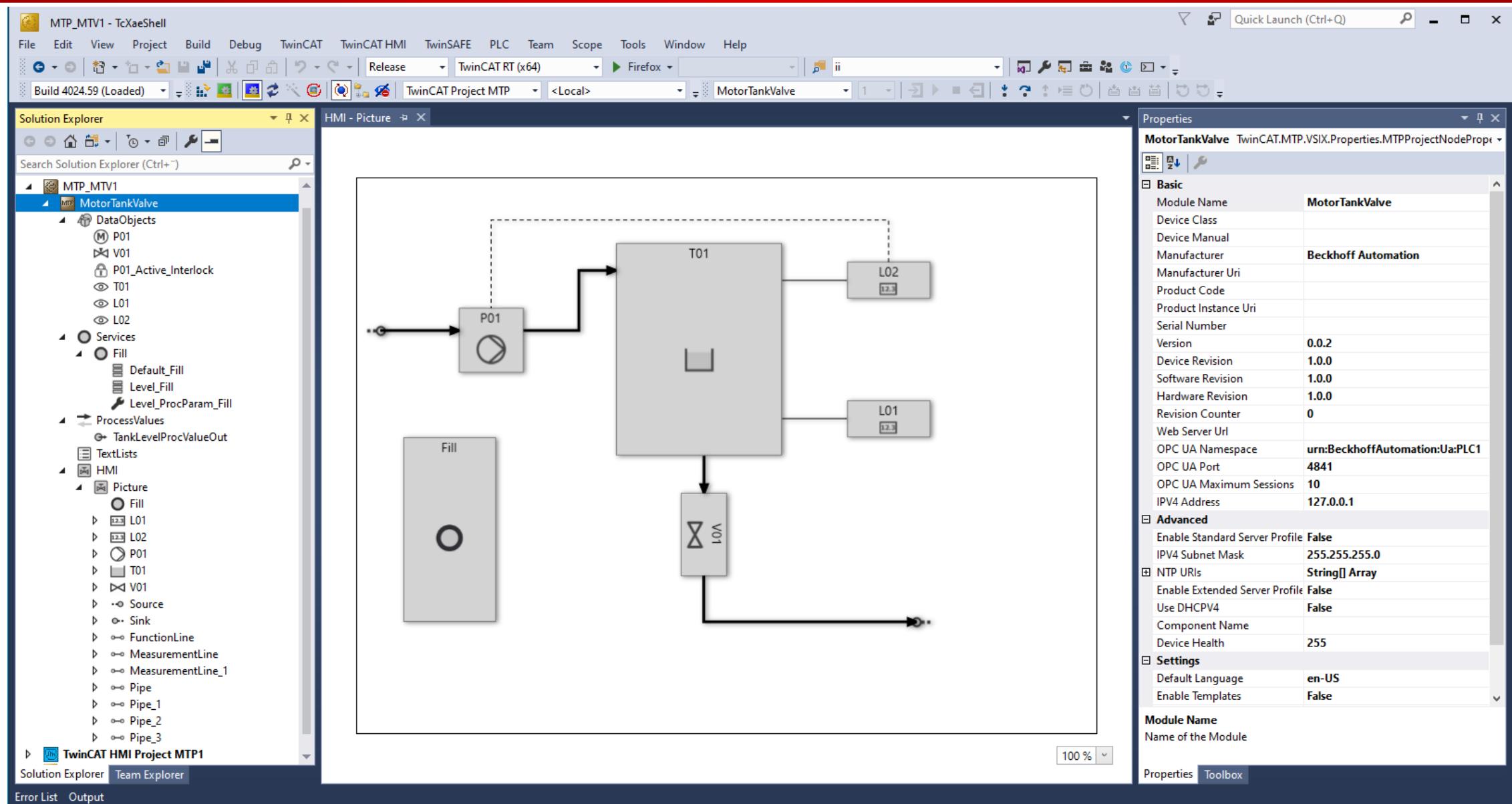


**So with TwinCAT MTP and
with the help of OPC UA,
we can quickly get from ...**



P&ID model and engineering

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Module engineering (PEA): Local HMI

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MTP_MTV1 - TcXaeShell

File Edit View Project Build Debug TwinCAT TwinCAT HMI TwinSAFE PLC Team Scope Tools Window Help

Build 4024.59 (Loaded) TwinCAT Project MTP1 <Local> MotorTankValve Desktop.view

Solution Explorer

Search Solution Explorer (Ctrl+Shift+F)

TwinCAT HMI Live...HMI Project MTP1 Project Properties

Project: TwinCAT HMI Project MTP1

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Diagram Description: A process flow diagram for a motor tank valve system. It shows a source connected to a pump (P01), which feeds into a tank (T01). The tank has two outputs: one to a valve (V01) labeled 'CLOSED' and another to a level indicator (L01). The tank also has an outlet to a valve (V02) labeled 'OK'. Below the tank is a pump (P01) with a status indicator 'O M' and a float switch '38.70 %'. A valve (V01) is shown below the tank. A pump (P01) is at the bottom with a status indicator 'OK'.

Properties

TwinCAT HMI Project MTP1 Project Properties

Build Information

- Creation: 11.11.2024 16:22
- Product Version: 1.12.762.46

Creator

- Default Viewport Height: 800
- Default Viewport Width: 1024

Deployment

- Binding Symbol Error Handling: Ignore
- Interval [ms]: 200
- PostProcessing: True
- Subscription Mode: Change
- Theme Name: Base
- Timeout [ms]: 20000
- Timeout [ms] (System): 60000
- Title: MTP MotorTankValve demo
- Verbose Level: ErrorsWarnings
- Version: 1.0.0.0

General

- Company Name: Beckhoff Automation
- Company's Website: Default
- LoginPage: ScaleToFit
- Scale Mode: Startup View
- Startup View: Desktop.view

Misc

- Pin version: True (Version 1.12.762.46)
- Project File: TwinCAT HMI Project MTP1.hmiproj
- Project Folder: C:\TCprojects\MTP0818_projects\MTP
- System Popups: Beckhoff.TcHmiPopups

Region and Language

- Default Language: (Use Browser Default)
- Localization Fallback: --
- Time Format Locale: (Use Browser Default)

Binding Symbol Error Handling

Determines how a binding will handle symbol related errors. Possible values:- Reset: Forward the default toggle switch (null) to force...

Properties Toolbox

Add to Source Control

Plant engineering (POL) and orchestration

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The screenshot displays a plant engineering (POL) and orchestration interface for a MotorTankValve_v2 system.

HMI Overview: The main window shows a schematic diagram of the valve assembly. A pump (P01) is connected to a tank (T01) at 41.86% level. The tank is connected to a valve (V01). A limit switch (L01) is shown as ON, and a limit switch (L02) is shown as OFF. A local control panel (P01) indicates a current speed of 20.00% and a setpoint speed of 20.00%. It also shows errors (Trip) and locks (Interlock).

Service Procedures (control strategies): A table lists two service procedures:

ID	Name	Description
2	Level_Fill	Self-completing? = true
1	Default_Fill	Self-completing? = false

Master recipe: The Master_recipe_Fill (v1) is currently in edit mode. The flowchart includes nodes for Recipe_Function_Initialization, Level_Fill_MotorTankValve_Fill, and Recipe_Function_End.

Bottom Navigation: The navigation bar includes links for User, Administrator, Services, and a timestamp: 11.6.2025 12.08.40.

Thank you for your attention!

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- TwinCAT MTP beta available for Twincat 3.1 Build 4026 and support MTP 2.0 standard specification
- Other beta versions and further information also available: processindustry@beckhoff.com