

## ROS UTILISATION AS A COMPONENT IN AGV APPLICATIONS

FIIF Event: Robot Operating System  
(Thursday, September 22, 2022 at 9:00-12:30)

Jouni Sievilä  
VP Engineering





## Navitec Systems – 1998 to 2022

- Privately held. Focus on OEM market
- Entered material-handling market in 2013 with major success
- Engineering company, technology leader

**Founded in 1998 with AGVs  
for mining automation  
(natural feature navigation)**





# Navitec Systems – 1998 to 2022

1998



Navitec was founded.  
Market leader in natural feature navigation in the mining industry.



2004



First natural feature navigation system delivered to Chile

2008



Nuclear Waste AGV with Natural Feature Navigation.  
Swedish national nuclear depository.

# Navitec Systems – 1998 to 2022

2013



\*Käyköni testikalvoksen aukes Sandvikin Tampereen tehtaan pihalla.  
\*Se on mahdollistaa prototyypin nopean kehityksen ja testaamisen.

Finnish engineering award

2014



Complete software solution for material-handling AGVs systems

2020



Fastest growing company award by Deloitte



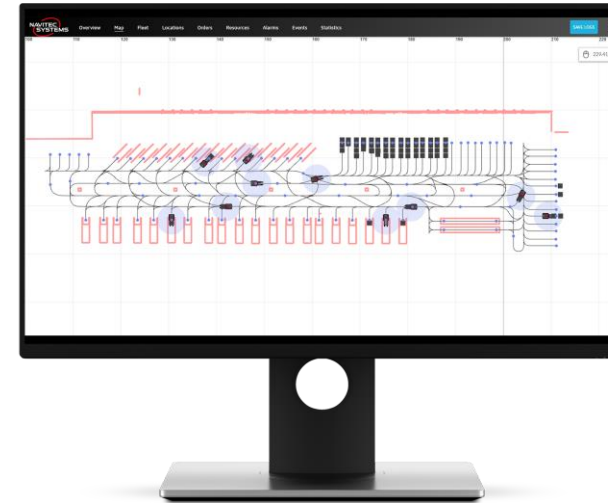
# Navitec Systems – 1998 to 2022

2021



New office in Germany, Hamburg

2022



Complete automation system for multiple vehicles with WMS integration, VDA 5050, new Fleet Control.



## Navitec Systems – 1998 to 2022

**Now: 45 employees, all engineers**  
**Growing fast**

Headquarter in Espoo, Finland (near Helsinki)

Distributors in South-Korea, Japan, Malaysia, Philippines, Singapore, Thailand, Vietnam and Turkey

Sales office in Oldsmar, Florida, USA

Wholly owned subsidiary in Hamburg, Germany



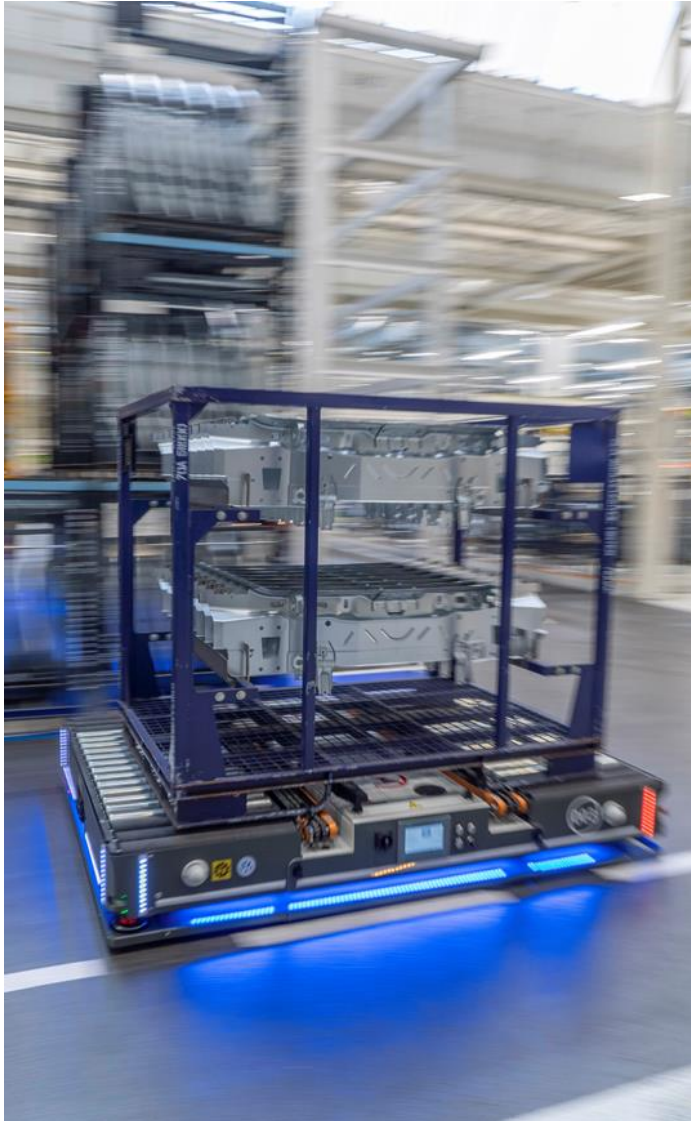


## CUSTOMERS AGVs





# CUSTOMERS AGVs





## CUSTOMERS AGVs



## CUSTOMERS AGVs



SOLTEQ



## CUSTOMER AGV VIDEOS – QUICK OVERVIEW





# NAVITROL NAVIGATION

## POSITIONING AND VEHICLE CONTROLS

### POSITIONING

- Natural feature navigation
- No reflectors needed
- Minimal amount of natural features required for stable navigation

### Sensor fusion

- 2D laser
- IMU
- Differential GPS
- 3D laser
- Radar
- 2D and 3D camera
- Full Dynamic Mapping
- Indoor and full outdoor navigation

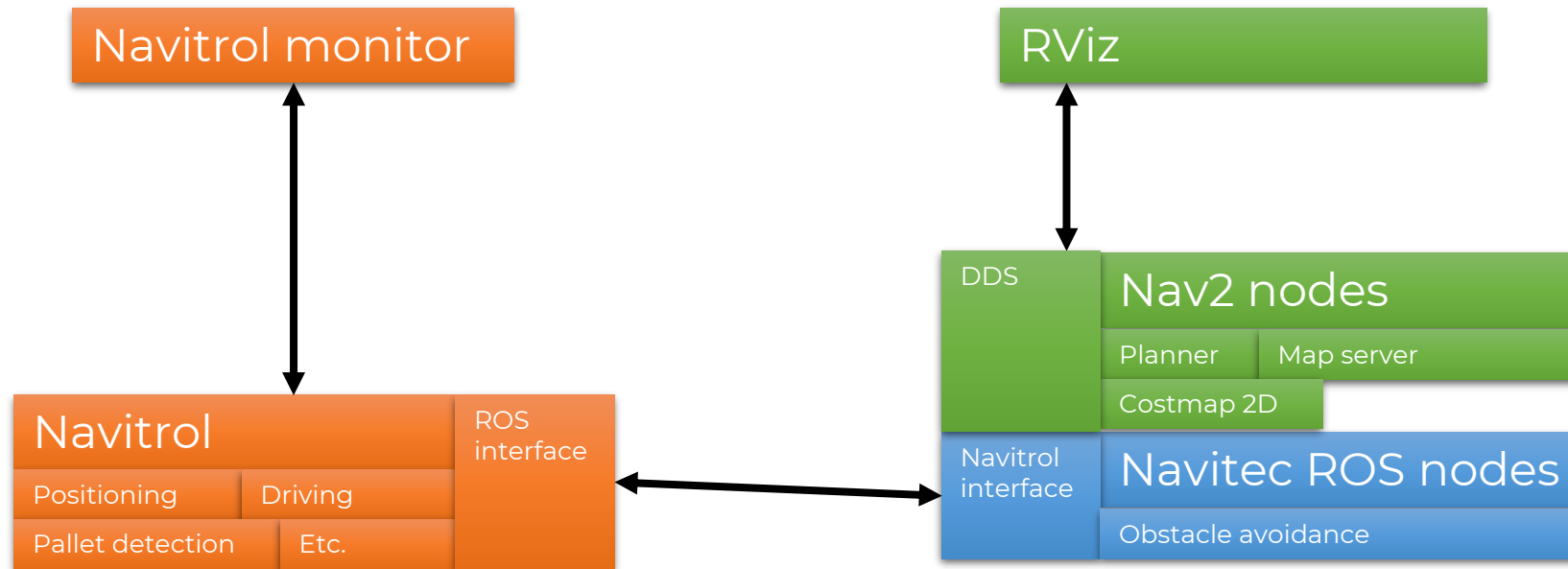
### VEHICLE CONTROLS

- Any type of vehicle and wheel geometry
- Fully configurable
- Hardware independent
- Open architecture

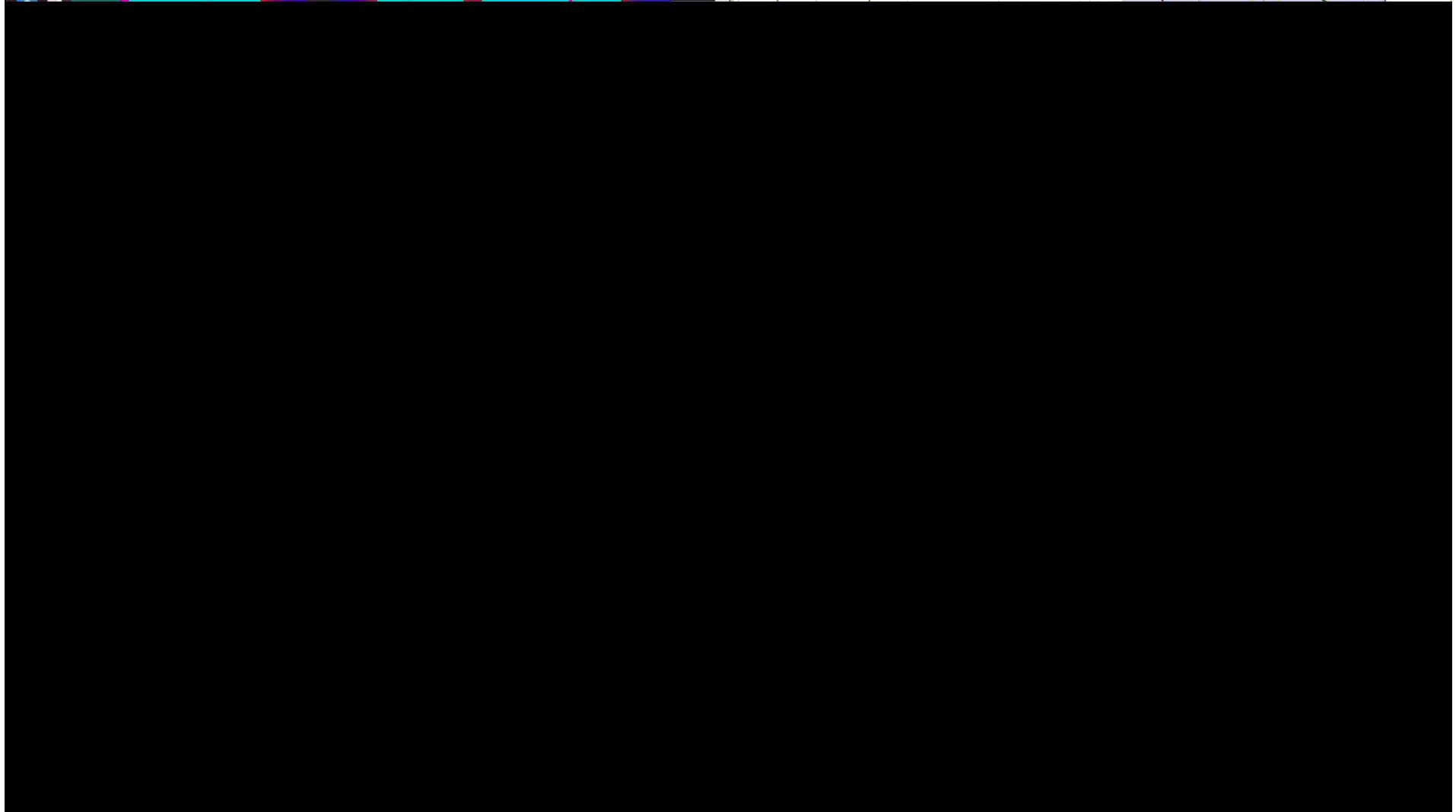
### Special functionalities

- Driving in formation
- Synchronized driving
- Automated load station & docking station detection
- Racking
- Block-stacking
- Pallet detection
- Obstacle avoidance

# ARCHITECTURE

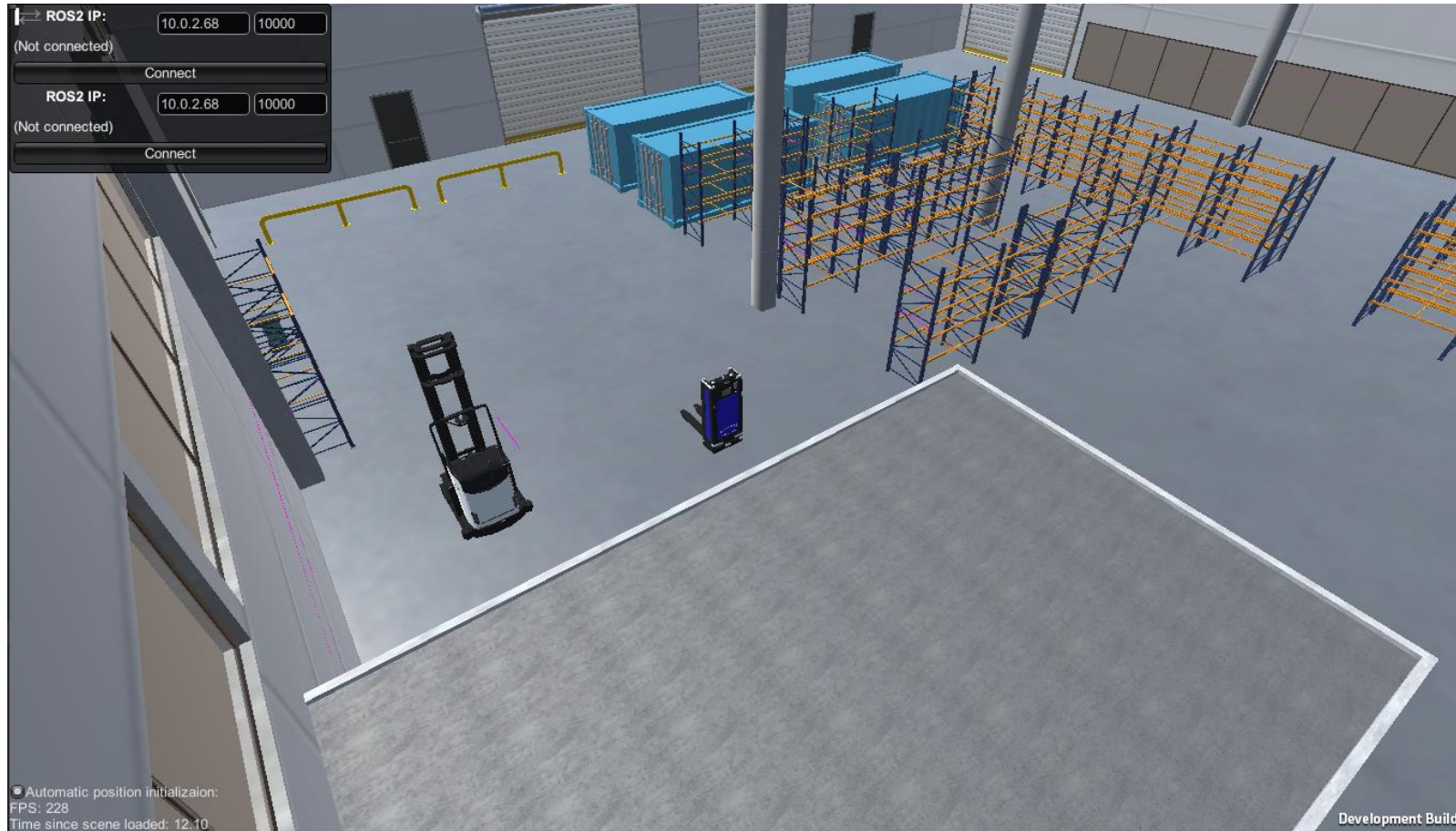


# ROS2 BASED OBSTACLE AVOIDANCE





# PEAMS INDOOR DEMO





## CONTACT US

### ENGINEERING

**Jouni Sievilä, VP Engineering**

+358 50 4042373

[jouni.sievila@navitec.fi](mailto:jouni.sievila@navitec.fi)

Helsinki, Finland, (GMT+2)

### SALES (inquiries worldwide)

**Matthias Otto, VP Global Sales**

+1 727 424 6968

[matthias.otto@navitecsystems.com](mailto:matthias.otto@navitecsystems.com)

Florida, USA, East Coast, (GMT-5)

**Hannah Koch, Sales And Application**

+358 401989622

[hannah.koch@navitec.fi](mailto:hannah.koch@navitec.fi)

Helsinki, Finland, (GMT+2)

### SERVICE DEPARTMENT FINLAND (Headquarter)

**Aleksi Itkonen, Director of Engineering – Product Support**

Phone: +358 40 827 3524

[aleksi.itkonen@navitec.fi](mailto:aleksi.itkonen@navitec.fi)

Helsinki, Finland, (GMT+2)

