Logisnext Solutions

Logisnext

Case Mitsubishi Logisnext AGVs: ROS in perception-based local navigation

Anna-Kaisa Repo

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MITSUBISHI LOGISNEXT EUROPE

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Introduction to

Mitsubishi Logisnext

We are Part of Mitsubishi Heavy Industries

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ENERGY >



AIRCRAFT >



SPACE >



SHIP & OCEAN >



TRANSPORTATION >



MATERIAL HANDLING >



ENVIRONMENT >



AUTOMOTIVE >



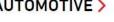
INDUSTRIAL MACHINERY >



INFRASTRUCTURE >



LIVING & LEISURE >





DEFENSE >



MHI group consists of multiple strategic business units under seven domains:

- Energy Systems
- Plants & Infrastructure Systems
- Logistics, Thermal & Drive Systems

- Nuclear Energy Systems
- Machinery Systems

- Integrated Defence & Space Systems
- Commercial Aviation Systems



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VISION:

Moving the world forward as the leading provider of innovative logistics and material handling solutions



Introduction to

Logisnext Solutions

Background and Experience



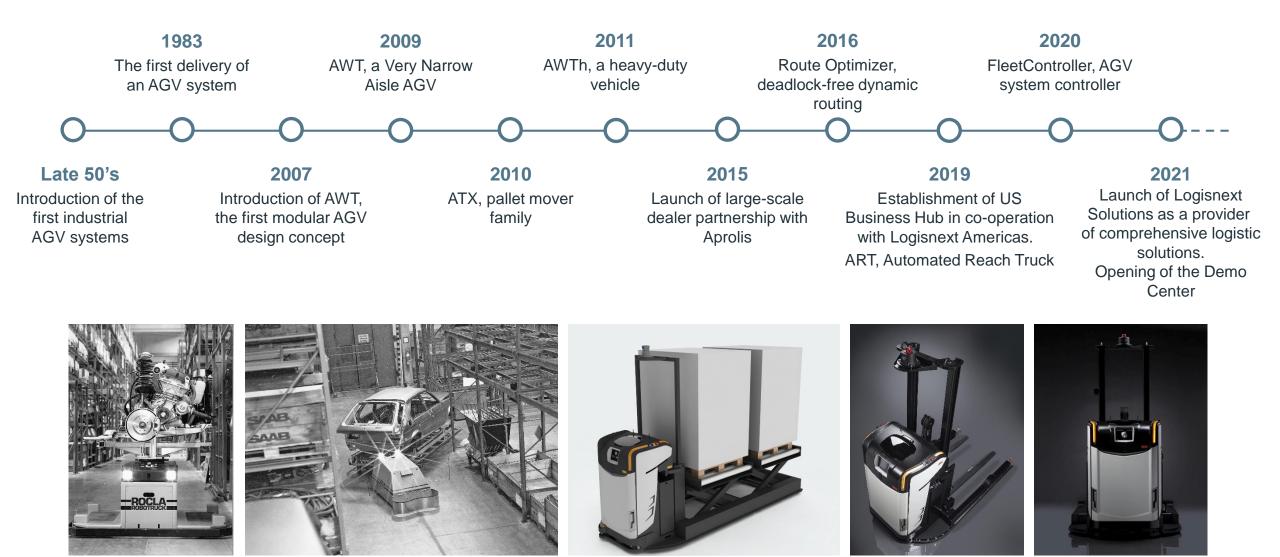


Mitsubishi Logisnext Europe (MLE) has an unparalleled experience in the intralogistics automation.

Our background is in Rocla Automated Guided Vehicle (AGV) Solutions:

- 40+ years of experience.
- Over 8,000 AGVs.
- Over 2,000 projects worldwide.
- Global operations through a wide ML and partner network.





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Global Services:

- Full service portfolio scalable according to customer demands.
- Customer support through 24/7 helpdesk.
- On-site support through 35 subsidiaries and over 1,000 dealers worldwide.

Logistic Solutions

MLA

Mitsubishi Logisnext Americas:

- Direct Sales
- Partner Network
- 1. Global & Local integrators
- 2. MLA Network

MLE

Mitsubishi Logisnext Europe:

- Direct Sales
- Partner Network
- 1. Global & Local integrators
- 2. MLE Network

- ML Mitsubishi Logisnext:
- Direct Sales
- Partner Network
- 1. Global & Local integrators
- 2. APAC Network



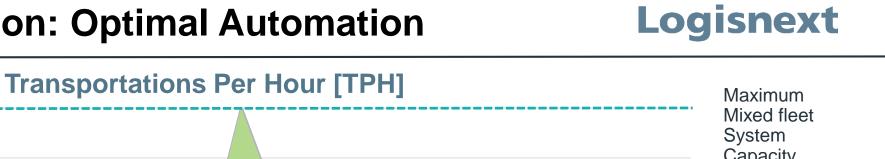
Our Vision: Optimal Automation

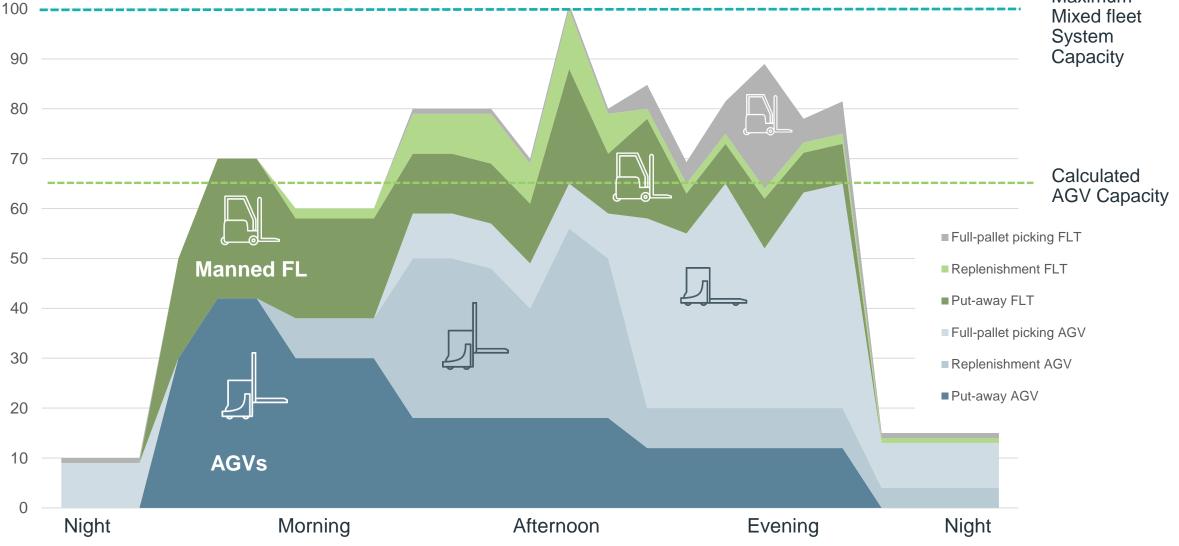
Logisnext Solutions

Optimal Automation: Strengths of Both Worlds

	Mixe		
Humans		<u> </u>	Robots
Prone to errorsTend to fatigueUnpredictable	 > Flexible & adaptive > Creative & intuitive > Handy & skilful 	 Predictable & tireless Safe & reliable Productive & efficient 	 Don't do creative problem solving Non-intuitive
	> Human workforce can focus on more motivating tasks	 Robots can handle repetitive tasks more efficiently 	

Mixed Fleet Solution: Optimal Automation

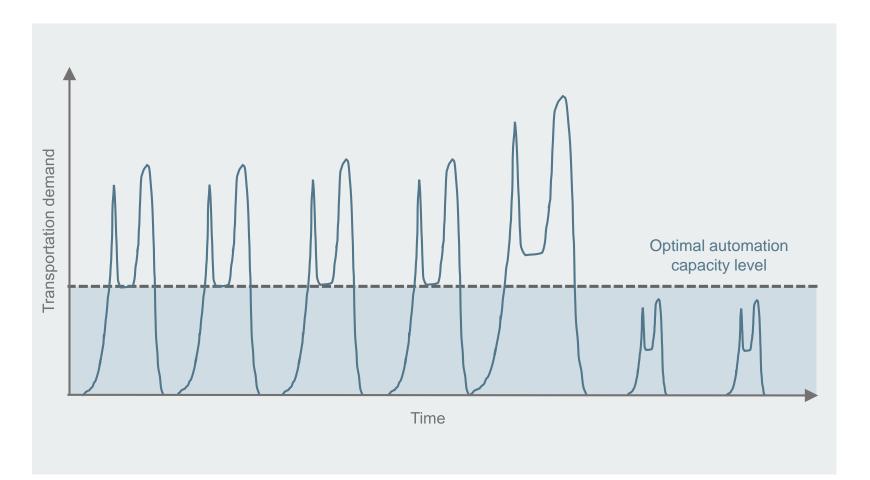




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Material Flows





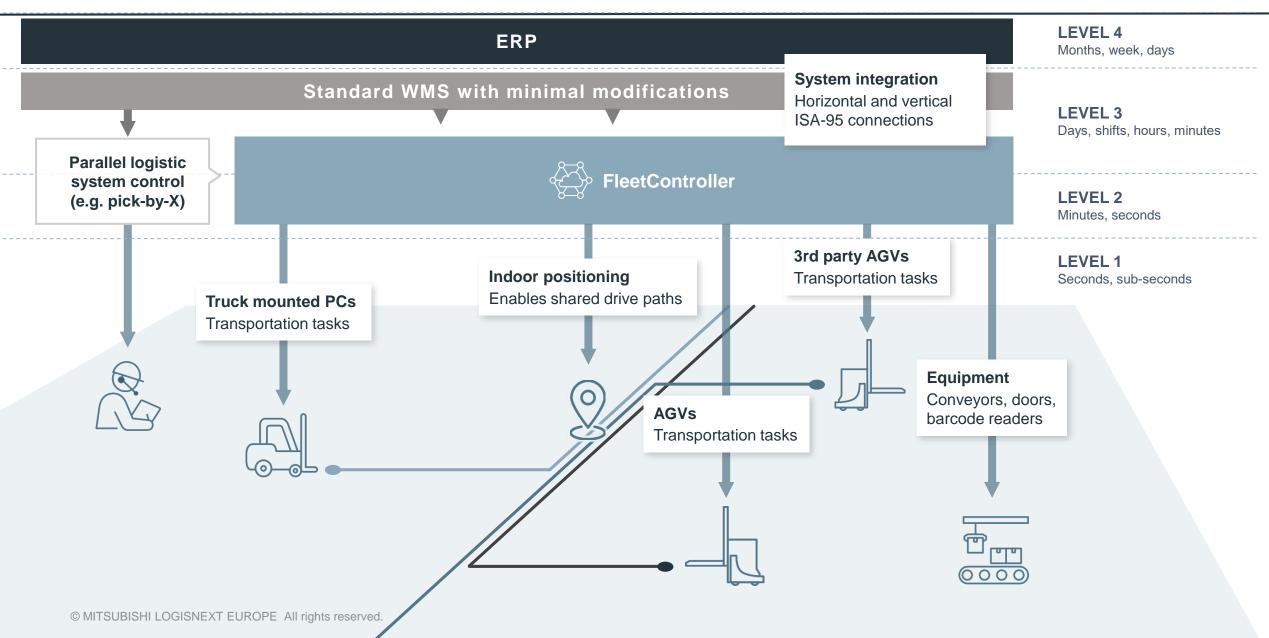
Normal variation in the transportation demand

- Peak vs. average demand
- How many shifts per day
- Seasonal changes

Continuously changing environment

- New material flows
- Bottlenecks in the layout or transportation demand

Seamless Collaboration



Mixed Fleet Levels

Mixed fleet levels	Isolated	Co-existing	Co-operating	Collaborating	مرمہ <u>خ</u> Optimizing	Self-learning
			Logisnext 2022		Logisnext 2023	
		Complementary automation	Flexible capacity	Orchestrated automation	Assisted optimal driving	To infinity and beyond
	State-of-the-art in logistics industry					Level of Human- Automation Interaction
Customer benefit in a nutshell	Automation in specific process	Automation applicable in sub-processes	Right-sized investment and flexible capacity	Focus on complete material flow efficiency	Optimized process efficiency	Continuously optimizing

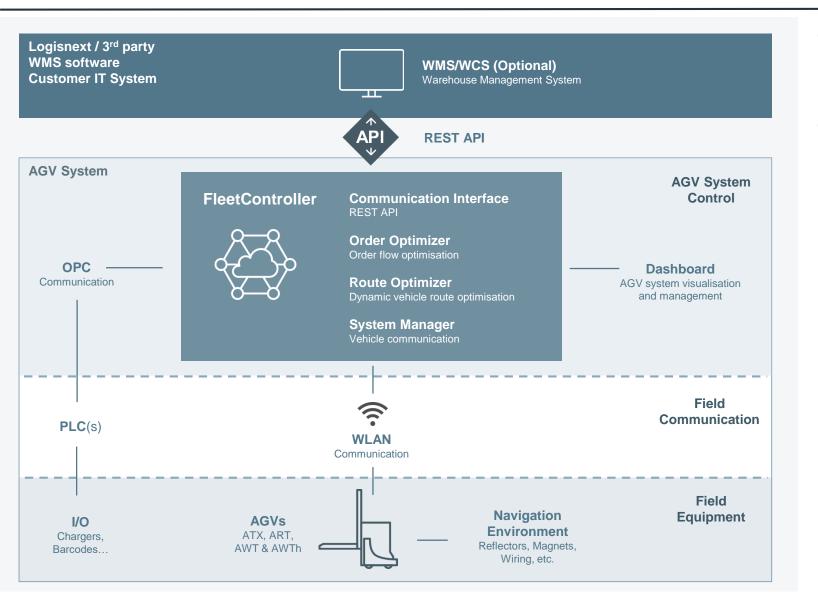


Case Pallet Finder

ROS in perception-based local navigation

AGV System Integration with FleetController

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The AGV system software:

Connects WMS/WCS/WES/ERP with AGVs.

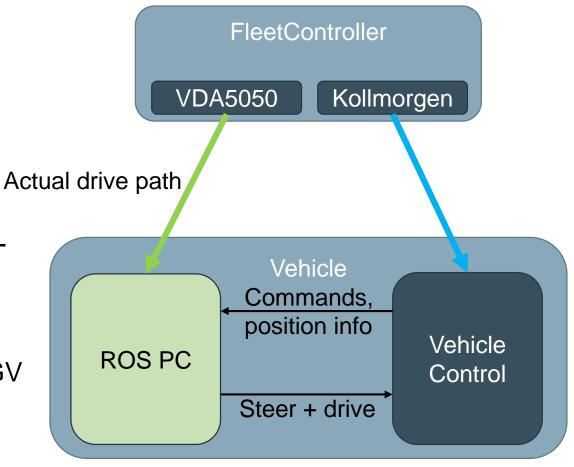
Tailor-made intelligence:

- Continuous computing to maximise transport capacity.
- Optimisation logic scales automatically to material flow demands.

Integration:

- Connects to WMS with REST API, a widely used way to integrate systems.
- Manages the AGV fleet according to WMS orders.
- Interacts with the site and surroundings through various technologies, such as barcodes or I/Os.

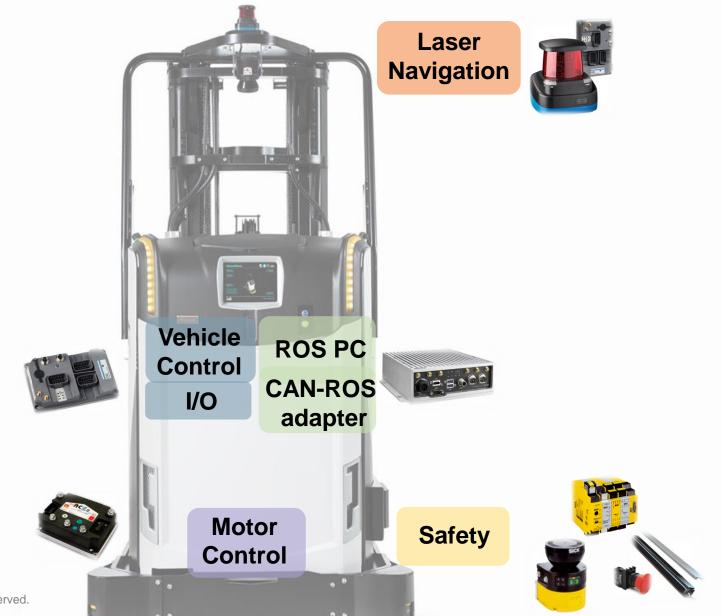
- Traditional Kollmorgen load-handling interfaces are used to send operation parameters and codes to vehicle
- Vehicle controller listens to steer and drive inputs from ROS PC
 - Kollmorgen guidance-loop replaced by a pathfollowing controller, with paths generated by a pathplanner in FleetController.
 - PalletFinder results from individual lidar scans are sent over CAN-bus
 - Kalman filter applied to both pallet estimate and AGV location, where the all measurement results are affecting the overall estimate



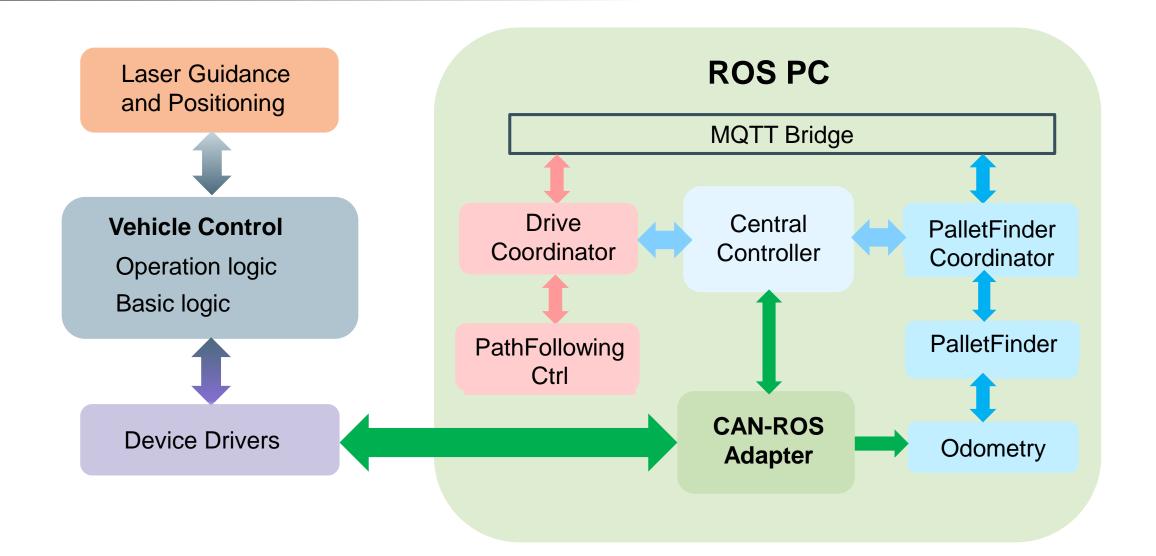




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Human-Machine Collaboration



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<u>Video</u>

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Trajectory planning with human-like problem solving skills.

WHY Business Case: Interoperability

HOW Enables: Fast and Agile R&D

WHAT Result: Automatic becomes Autonomous



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